15th International Carpathian Control Conference – List of accepted papers

1.	Anna Filasova, Vratislav Hladky and Dusan Krokavec
	Static output control design reflecting fuzzy subsystem interactions in TS fuzzy models
2.	Vojtech Vesely and Daniel Vozak
	Stable model predictive controller design
3.	Mikulas Huba
	Tuning of a filtered pole assignment controller for an integral plant
4.	Igor Belai and Mikulas Huba
	Comparison of two approaches to a positional servo control
5.	Dusan Krokavec and Anna Filasova
	Output PI control of MIMO linear continuous-time systems
6.	Adrian Ilka and Vojtech Vesely
	Discrete Gain-Scheduled Controller Design: Variable Weighting Approach
7.	Alena Kozáková, Róbert Krasňanský and Vojtech Veselý
	Switched System Controller Design: the Frequency Domain Approach
8.	David Soós and Mikuláš Huba
	Experimental performance portrait based optimal controller tuning
9.	Milos Seda
	From Classical Transportation Problem to Crop Problems with Uncertatinty
10.	Stanislav Vrána and Bohumil Šulc
	Neural Network Inference of Biomass Fuel Moisture During Combustion Process
11.	Ivor Dülk and Tamás Kovácsházy
	A Computationally Effective Method for Calculating the Exponential Fit
12.	Béla Rima, József Vásárhelyi, János Végh and Jan Turán
	Mojette Transform implemented in Labview
13.	Dominik Sierociuk and Michal Macias
	Initial conditions for a recursive constant and variable fractional-order derivative and its verification
	based on analog model
14.	Alena Vagaská, Peter Michal, Miroslav Gombár, Ján Kmec, Emil Spišák and Miroslav Badida
	Modelling of the Anodizing Process of Aluminum Using Neural Networks
15.	Karol Kostur
	Optimization of burner's range of tunnel furnace by simulation
16.	Roman Prokop, Jiří Korbel and Radek Matušů
	Autotuning for Delay Systems – An Algebraic Approach
17.	Michal Kašpárek
	Glass window vibrations analysis used for positioning of piezoelectric damping elements
18.	Jiri Otahal and Frantisek Hruska
	Aspects of electromagnetic interference in range of low frequencies
19.	Jiri Tuma, Miroslav Mahdal, Pavel Šuránek and Marek Babiuch
20	Simulation of the parametric vibration damping
20.	Marcin Węgrzynowski
21	MR damper control in an energy-harvesting vibration reduction system
21.	Magdalena Zawartka Sonsitivity analysis of the MP damper model parameters on the vibration transmissibility
	Sensitivity analysis of the MR damper model parameters on the vibration transmissibility characteristics
22	
22.	Mateusz Romaszko, Sebastian Pakuła and Jacek Snamina Composite beam's parameters identification based on frequency response
	Composite beam's parameters identification based on frequency response

23.	Beáta Stehlíková and Patrik Flegner
23.	Possibilities to compare vibration in drilling rock
24.	Marcin Węgrzynowski
24.	Electromechanical transducers to supply an MR rotary damper: laboratory testing
25.	G. Serdar Tombul
25.	Real Time Control of a Fin Loading System
26.	
26.	Igor Podlubny and Bohdan Datsko
27.	Recent advances in methods for studying and solving partial fractional differential equations Leszek Cedro
27.	
20	Linearization and Identification a Mathematical Model of an Excavator
28.	Ivo Petras
	Practical aspects for implementation of fractional-order controllers
29.	Marcela Pavlickova and Ivo Petras
	A note on time series data analysis using a fractional calculus technique
30.	Monika Žecová, Ján Terpák and Ľubomír Dorčák
	The Modeling of Heat Conduction Using Integer- and Fractional-Order Derivatives
31.	Michał Sobolewski and Zbigniew Koruba
	Optimal Control and Stabilization of the Observation- Tracking Device Placed on a Deck Of Unmanned
	Aerial Vehicle (UAV)
32.	Paweł Drąg and Krystyn Styczeń
	Necessary optimality conditions for optimal control of multistage DAE systems
33.	Cyril Oswald, Viktor Plaček and Bohumil Šulc
	Advanced Control with Economic - Ecological Optimization for Biomass-fired Boilers
34.	Tomáš Barot and Marek Kubalčík
	Predictive Control of Non-Minimum Phase Systems
35.	Ondřej Ježek
	Case study on an event model-based PID control of a thermal process
36.	Miluše Vítečková and Antonín Víteček
	Dominance of poles for desired model method
37.	Pavol Bistak and Mikulas Huba
	Constrained Pole Assignment Control of a Two Tank System
38.	Danica Rosinova and Ivan Holič
	LMI approximation of pole region for discrete-time linear dynamic system
39.	Josef Cernohorsky and Marcel Horák
	Vertical Climber 2 - design and implementation of control algorithm
40.	Dean Brennan and Jan Kolaja
	Real Time Location System using Passive UHF RFID tags
41.	Viliam Dolinay, Lucie Pivnickova and Vladimir Vasek
	Objectivization of traditional otonerological examinations based on Kinect sensor
42.	Alois Krejci, Tomas Popule and Martin Goubej
	Closing the motion control loops via industrial Ethernet network
43.	Jaroslav Antoš and Martin Bušek
	Client-Server Application for the operator panel Weintek and the control system Siemens Simotion
44.	Balázs Scherer and Gábor Horváth
	Microcontroller tracing in Hardware In the Loop tests
45.	Tamás Kovácsházy and Bálint Ferencz
	One-way Delay Measurement System for Local Area Network Delay and Jitter Characterization
46.	Aleksejs Zacepins and Jurijs Meitalovs
	Implementation of multi-node temperature measurement system for bee colonies online monitoring
47.	Adam Wolniakowski, Piotr Kozioł and Kanstanstin Miatliuk
	Genereting trajectory for 5 DoF serial link CNC machine with kinematic constraints
48.	Oto Haffner
	Making of environment map using a laser rangefinder and library OpenCV
	1 - 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1 -

49.	Miroslav Köver-Dorčo
	Scada System Creation by Using Java Applications and PLC
50.	Marián Hruboš, Aleš Janota and Rastislav Pirník
	Road surface measurement and visualization based on data from the laser scanner.
51.	Marian Mrosko, Jozef Skultety and Eva Miklovicova
	Laguerre Network Implementation in Industrial Control Systems
52.	Ján Piteľ and Mária Tóthová
	Dynamics of the Pneumatic Muscle Actuator: Measurement and Modeling
53.	Wojciech Lepiarz
	The vision analysis of a McKibben pneumatic artificial muscle
54.	Dorota Marszalik
	Application of Haptic Omni Device to Determination of the Setpoint Trajectory
55.	Pavel Šuránek, Miroslav Mahdal and Jiří Tůma
	Modelling and Simulation of an Active Damped Structure
56.	Václav Řepa and Ondrej Železník
	Methodological Limitations of Modeling Languages BPMN and ARIS
57.	Erik Kučera and Branislav Hrúz
	Modelling of automated storage systems using Hierarchical Coloured Petri nets
58.	Agata Nawrocka, Karolina Holewa and Kanstantsin Miatliuk
	Conceptual Design of Brain Computer Interface in the Formal Basis of Hierarchical System
59.	Vladena Baranova, Lenka Landryová and Jozef Futo
	Application of multivariate planning methods in determining KPI of rock disintegration process
60.	Petr Podešva and David Fojtík
	Calibration of 2D scanner with nonlinearities
61.	Ivan Svarc
	Contributions to the Application of Popov and Circle Criterion for Stability Analysis
62.	František Vdoleček
	Sensor and Control Result
63.	Lenka Landryová and Patrik Urban
	A Laboratory Stand for Testing the ABS Unit Model
64.	Marek Babiuch
	.Net Microframework Gadgeteer Measurement Applications Development.
65.	David Fojtík
	Measurement of the Volume of Material on the Conveyor Belt
66.	David Fojtík and Petr Podešva
	The system for measuring deformations during welding
67.	Jolana Škutová
	A Web Based Application Using Matlab Builder NE for The Analysis of Linear Systems
68.	Petr Podešva, David Fojtík and Jan Gebauer
	Automation of Measurement and Data Collection for Gas Filling Line
69.	Michal Radecký and Pavel Smutný
	Evaluating user reaction to user interface element using eye-tracking technology
70.	Jan Nádvorník and Pavel Smutný
	Remote Control Robot Using Android Mobile Device
71.	Škuta Jaromír
	The control unit with wireless interfaces for CNC model
72.	Ales Lebeda and Petr Pivonka
	Comparison of Offline Identification Methods on Bounded AR Polynomial Models
73.	Istvan Oniga and József Sütő
	Elder people supervision by IoT techniques
74.	Bogdan Sapinski, Wojciech Horak and Andrzej Sioma
	Experiments on MR Fluid Behaviour in the Squezee Mode Using the Vision Method
75.	Stanislaw Flaga and Ireneusz Dominik

	Characteristics of the flow control valve with MSMA actuator.
76.	Piotr Micek and Paweł Hammer
	Control system in the laboratory stand to the continuous casting of aluminum
77.	Marcin Nawrocki and Agata Nawrocka
	Artificial neural networks for identification in real time of the robot manipulator model parameters
78.	Agata Nawrocka, Andrzej Kot and Marcin Nawrocki
	Fuzzy logic controller for rehabilitation robot manipulator
79.	Andrzej Kot and Agata Nawrocka
	Modeling of human balance as an inverted pendulum
80.	Łukasz Nocoń and Zbigniew Koruba
	Programmed Control of the Flat Track Anti-Tank Guided Missile
81.	Agata Nawrocka and Karolina Holewa
	Emotiv EPOC neuroheadset in Brain – Computer Interface
82.	Daniel Gapiński and Izabela Krzysztofik
= '-	The process of tracking an air target by the designed scanning and tracking seeker
83.	Iveta Onderová and Ľudovit Kolláth
	Testing and verification of selected technological parameters of the parallel kinematic structure
84.	Milada Omachelová, Eva Kureková, Martin Halaj and Ilja Martišovitš
0	Theoretical aspects of control of the Tricept type parallel kinematic structure
85.	Cyril Belavý, Filip Vitáloš, Marcel Vlček, Dana Šišmišová and Marek Michalečko
03.	Robust Control Synthesis for a Class of Distributed Parameter Systems
86.	Anna Vasičkaninová and Monika Bakošová
ю.	Control of a heat exchanger using Takagi-Sugeno fuzzy models
87.	Martin Jarčuška, Milan Žalman, Tatiana Mudráková and Pavol Varga
67.	
00	Modelling and Effective Controlling of Radial Electromagnetic Bearings Marian Šofranko and Róbert Zeman
88.	
	Simulation of pipeline transport backfill mixtures
89.	Karol Kostur
	Mathematical modeling temperature's fields in overburden during underground coal gasification
90.	Marek Laciak, Ján Kačur, Milan Durdan and Patrik Flegner
	Application of optimization method for optimal control of the steelmaking process
91.	Alena Paulíková and Ondrej Železník
	Multicriterial Analysis of Factors Considering Intensity and Extent of Floods
92.	Ján Terpák, Pavel Horovčák, Miloš Horváth and Monika Žecová
	The proposal of web service for support of specific thermochemical calculation
93.	Igor Leššo, Patrik Flegner, Pavel Horovčák, Beáta Stehlíková and Zuzana Sabova
	Some Problems in Control of the Quality of the Process of Rotary Drilling of Rocks by Using Suitable
	Visualization of Concurrent Vibrations
94.	Matúš Tatarko, Ján Tóth, Ľuboš Ovseník, Ján Turán and József Vásárhelyi
	FSO availability estimation from measurements on TUKE experimental system
95.	Pavol Liščinský and Vladimír Serbák
	Fault detection based on Linear Quadratic control performance in nonlinear systems
96.	Tomáš Mravec and Peter Vestenický
	Increasing Objects Localization Precision by Determination of Inertial Sensor Calibration Constants
	Using Differential Evolution Algorithm
97.	Michal Kocúr, Stefan Kozak and Branislav Dvorscak
	Design and Implementation of FPGA - Digital Based PID Controller
98.	Peter Valach and Danica Rosinova
55.	Switched system robust control: pole-placement LMI based approach
99	
99.	l lán Durech, Fmilia Bubeniková and Mária Francková
99.	Ján Ďurech, Emília Bubeníková and Mária Francková Security solutions of intelligent transportation system's applications with using VANET networks
99. 100.	Ján Durech, Emilia Bubeniková and Mária Franeková Security solutions of intelligent transportation system's applications with using VANET networks Jan Halgas, Aleš Janota, Rastislav Pirník and Peter Holečko

101.	Dariusz Grzybek
400	Piezoelectric generator for the power supply of the monitoring system
102.	Michal Rost, Josef Smolka, Matej Mojzeš and Miroslav Virius
	Feature Space for Statistical Classification of Java Source Code Patterns
103.	Ivo Formánek, Radim Farana and Aleš Galuška
	Multidrive Systems in Continual Rolling Mills
104.	Miroslav Vavroušek
100	Pneumatic rotational engine behavior investigation and suitable control structure analysis
105.	Lucie Pivnickova, Viliam Dolinay and Vladimir Vasek
100	Evaluation of static posturography via the Wii Balance Board
106.	Radim Farana, Bogdan Walek, Michal Janošek and Jaroslav Žáček
407	Fuzzy-Logic Control in Fast Technological Processes
107.	Bogdan Walek, Jiří Bartoš, Cyril Klimeš and Radim Farana
100	Fuzzy tool for conducting information security risk analysis
108.	Bogdan Walek, Michal Janošek, Jaroslav Žáček and Radim Farana
	Adaptive Fuzzy Control of Thermal Comfort in Smart Houses
109.	Jaroslav Žáček and Michal Janošek
110	Optimized Heating for Systems with Long Time Delays: A Case Study
110.	Milan Javůrek and Ivan Taufer
444	Rigorous Using of Calibration
111.	Jiří Horák, Igor Ivan and David Fojtík
112	Large scale monitoring of public transport accessibility in the Czech Republic
112.	Jiri Holik and Lenka Landryová
	Control of a general distribution system
113.	Lacezar Licev, Marek Babiuch and Jan Tomecek
444	Object Recognition for Industrial Image
114.	Dusan Teichmann, Michal Dorda, Jakub Vitek, Vladimir Michalik and Vladimir Smrz
445	Unmanned Aerial Vehicles Routing Problem
115.	Michal Rusek and Filip Lorenz
116	Simulation model for regular operation of section
116.	Tomáš Kot, Václav Krys, Vladimír Mostýn and Petr Novák
447	Control System of a Mobile Robot Manipulator
117.	Zora Jančíková, Pavel Koštial, Ondřej Zimný, Marian Kubliha, Stanislav Minárik, Marcel Poulain and
	Messaoud Legouera
110	The neural network analysis of optical glasses transmittance
118.	Ivo Špička, Milan Heger and Ondřej Zimný
110	Programmable Logic Controllers and Transient Heat Models
119.	Darja Noskievičová, Kateřina Brodecká and Miroslav Mahdal
120	SW Support for CCC and CQC Control Charts
120.	Vladislav Vancura, Lukas Otte, Roman Danel and Dagmar Letavkova
121.	Mine gas monitoring data analysis
121.	Dagmar Letavkova, Simona Matuskova and Vladislav Vancura Airport Effectiveness Modelling
122.	Boris Jobbágy, Ján Karchňák and Dušan Šimšík
122.	Rehabilitation robotics and wearable sensors as trends of home rehabilitation
123.	Pavel Staša, Filip Beneš, Jiří Švub, Zdeněk Neustupa and Zdeněk Neustupa Jr.
125.	Monitoring and evidence of cars in private objects
124	Martin Bušek
124.	
125.	The problem of measuring the radial cam grinder BRV 300 - CNC Domokos Kiss and Gábor Tevesz
125.	A Steering Method for the Kinematic Car using C*CS Paths
126.	Krzysztof Hryniów and Konrad Markowski
120.	Parallel digraph-building algorithm for polynomial realisations
	i dranci digraphi-bunung algorithin for polynomia realisations

127.	Sebastian Pakuła and Jerzy Michalczyk
	Determination of the Probabilistic Characteristics of the Coefficient of Restitution, with an Application
	of Acoustic Measurements
128.	Konrad Stefański, Marta Grzyb and Łukasz Nocoń
	The analysis of homing of aerial guided bomb on the ground target by means of special method of
	control
129.	Olga Andrianova
	On a state feedback anisotropy-based control problem for linear discrete-time descriptor systems
130.	Arkadiy Kustov
	Anisotropy-based analysis and synthesis problems for input disturbances with nonzero mean
131.	Ján Vachálek, Michal Bartko and Ján Bizub
	Long-run On-line Identification with Hybrid Regularized Exponential Forgetting Method
132.	Stella Hrehova and Erika Fechova
	Gain knowledge of selected properties of artificial muscles using tools of Matlab.
133.	Nurdan Bilgin and Metin U. Salamci
	Determination of Optimal Feedback Gain Matrix for a Class of Nonlinear Systems
134.	Peter Ťapák and Mikuláš Huba
	Comparing 2DOF PI and DO-FPI controllers for the first-order plants
135.	Anton Pytel and Štefan Kozák
	Modelling and effective predictive control of gas turbine process
136.	Jan Ciganek, Filip Noge and Stefan Kozak
	Trajectory tracking with variable sampling using fuzzy logic controller
137.	Mikuláš Huba, Tomáš Malatinec, Patrik Hudačko and Vladimír Popelka
	Laboratory model helicopter control using a lowcost Arduino hardware
138.	Vladimir Popelka
	A self stabilizing platform
139.	Tomáš Mikluščak and Aleš Janota
	How to Predict Location in Smart Environment and for What to Use It?
140.	Tomáš Mravec and Peter Vestenický
	Increasing Objects Localization Precision by Determination of Inertial Sensor Calibration Constants
	Using Differential Evolution Algorithm